

CN208 Introductory Computer Programming

Week 6:- Execution Control (If, Switch)

By

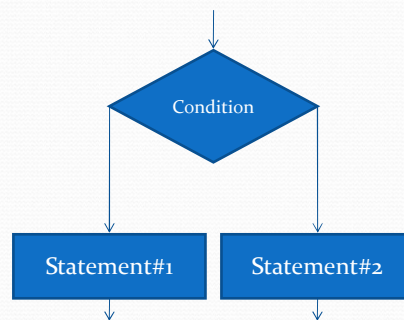
Dr. Piya Techateerawat

Execution Control (If, Switch)

- **Overview of Execution Control and Flowchart**
- If statements
- Switch Statements

Overview of Execution Control and Flowchart

- Flowchart requires control
- Decision making:- yes, no, again, skip
- Programming style = execution control



Execution Control (If, Switch)

- Overview of Execution Control and Flowchart
- **If statements**
- Switch Statements

If statements

```
if <logical expression 1>
    <code block 1>
elseif <logical expression 2>
    <code block 2>
    .
    .
elseif <logical expression n>
    <code block n>
else
    <default code block>
end
```

If statements

```
if day ==7                % Saturday
    state = 'weekend'
elseif day == 1          % Sunday
    state = 'weekend'
else
    state= 'weekday'
end
```

Execution Control (If, Switch)

- Overview of Execution Control and Flowchart
- If statements
- **Switch Statements**

Switch Statements

```
switch <parameter>
  case <logical expression 1>
    <code block 1>
  case <logical expression 2>
    <code block 2>
    .
    .
  case <logical expression n>
    <code block n>
  otherwise
    <default code block>
end
```

Switch Statements

```
switch month
case {9, 4, 6, 11}      % Sept, Apr, June, Nov
    days = 30;
case 2                  % Feb
    if leapYear
        days = 29;
    else
        days = 28;
    end
case {1, 3, 5, 7, 8, 10, 12} % the rest
    days = 31;
otherwise
    error('bad months index')
end
```

Sample Code

```
A = A/n^2;
A(1,1) = 1;
A(N,N) = 1;

b = sin(x);
b(1) = lefty;
b(N) = righty;

if(decision<3)

    % Find and plot the eigen values
    [e,v] = eig(A);
    e = diag(e);
    plot(real(e),imag(e),'rx');
    title('Eigen Values of the matrix');

elseif(decision>3)

    % Find and plot the eigen values of inv(A)
    [e,v] = eig(inv(A));
    e = diag(e);
    plot(real(e),imag(e),'rx');
    title('Eigen Values of the inverse of the matrix');
```

Sample Code

```
else

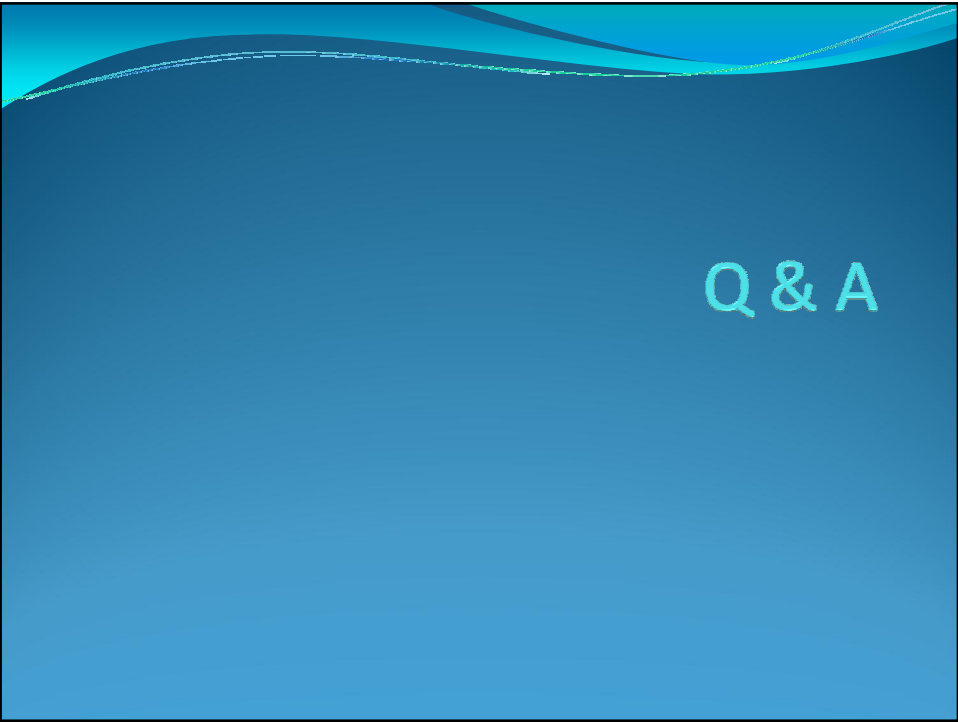
    % Solve the system
    y = A\b;
    linear = (lefty-righty+sin(leftx)-sin(rightx))/(leftx-rightx);
    constant = lefty + sin(leftx) - linear*leftx;
    true = -sin(x) + linear*x + constant;

    subplot(1,2,1);
    plot(x,y,'go',x,true,'y');
    title('True Solution and Approximation');
    xlabel('x');
    ylabel('y');
    subplot(1,2,2);
    plot(x,abs(y-true),'cx');
    title('Error');
    xlabel('x');
    ylabel('|Error|');

end
```

Reference

- <http://www.cyclismo.org/tutorial/matlab/if.html> @ 31 OCT 2008



Q & A